

Lineare Algebra II

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II a) ²No, because $\langle u, v \rangle = 3/5 \neq 0$
 $\langle u, w \rangle = 12/25 \neq 0$
 $\langle w, u \rangle = 4/5 \neq 0$

To be orthogonal all inner products with all vectors have to be zero.

b) ³ $\|su - 3v\| = (\langle su - 3v, su - 3v \rangle)^{1/2}$

$$= (\langle su, su \rangle + \langle -3v, -3v \rangle + 2\langle -3v, su \rangle)^{1/2}$$

$$= (25\langle u, u \rangle + 9\langle v, v \rangle - 30\langle u, u \rangle)^{1/2}$$

$$= (25\|u\|^2 + 9\|v\|^2 - 30 \cdot \frac{3}{5})^{1/2}$$

$$= (25 + 9 - 18)^{1/2}$$

¹⁾ $= (16)^{1/2} = 4$

c) Orthonormal basis for $\text{span}\left\{\begin{pmatrix} 4 \\ u \\ w \end{pmatrix}\right\}$

$$u_1 = \frac{1}{\|x_1\|} x_1 \quad \text{with } x_1 = u$$

$$u_1 = u$$

$$u_2 = \frac{1}{\|x_2 - p_1\|} (x_2 - p_1) \quad \text{with } x_2 = v$$

$$p_1 = \langle x_2, u_1 \rangle u_1$$

$$= \langle v, u \rangle u_1$$

$$= \frac{3}{5} u$$

$$u_2 = \frac{1}{\|v - \frac{3}{5}u\|} (v - \frac{3}{5}u)$$

$$\|v - \frac{3}{5}u\| = (\langle v - \frac{3}{5}u, v - \frac{3}{5}u \rangle)^{1/2}$$

$$= (\langle v, v \rangle + 9\langle u, u \rangle - 2\langle \frac{3}{5}u, v \rangle)^{1/2}$$

$$= (1 + \frac{9}{25} - \frac{6}{5} \cdot \frac{3}{5})^{1/2}$$

$$= (\frac{16}{25})^{1/2} = \frac{4}{5}$$

$$u_2 = \frac{1}{\|x_2 - p_1\|} (x_2 - p_1)$$

$$= \frac{5}{4} \left(v - \frac{3}{5} u \right)$$

$$u_3 = \frac{1}{\|x_3 - p_2\|} (x_3 - p_2) \quad x_3 = w$$

$$\begin{aligned} * p_2 &= \langle x_3, u_2 \rangle u_2 + \langle x_3, u_1 \rangle u_1 \\ &= \left\langle w, \frac{5}{4} \left(v - \frac{3}{5} u \right) \right\rangle \frac{5}{4} \left(v - \frac{3}{5} u \right) + \langle w, u \rangle u \end{aligned}$$

$$= \left(\frac{5}{4} \langle w, v \rangle - \frac{3}{4} \langle w, u \rangle \right) \frac{5}{4} \left(v - \frac{3}{5} u \right) + \langle w, u \rangle u$$

$$= \left(\frac{5}{4} \cdot \frac{12}{25} - \frac{3}{4} \cdot \frac{4}{5} \right) \frac{5}{4} \left(v - \frac{3}{5} u \right) + \frac{4}{5} u$$

$$= \left(\frac{12}{20} - \frac{12}{20} \right) \frac{5}{4} \left(v - \frac{3}{5} u \right) + \frac{4}{5} u$$

$$= \frac{4}{5} u$$

$$u_3 = \frac{1}{\|w - \frac{4}{5} u\|} \left(w - \frac{4}{5} u \right)$$

$$\left(\left\langle w - \frac{4}{5} u, w - \frac{4}{5} u \right\rangle \right)^{1/2} = \left(\langle w, w \rangle + \frac{16}{25} \langle u, u \rangle - 2 \cdot \frac{4}{5} \langle u, w \rangle \right)^{1/2}$$

$$= \left(1 + \frac{16}{25} - \frac{8}{5} \cdot \frac{4}{5} \right)^{1/2}$$

$$= \left(\frac{25}{25} + \frac{16}{25} - \frac{32}{25} \right)^{1/2}$$

$$= \left(\frac{9}{25} \right)^{1/2} = \frac{3}{5}$$

$$u_3 = \frac{5}{3} \left(w - \frac{4}{5} u \right)$$

Dus orthonormale span van $\text{span}(\{u, v, w\})$
 $= \text{span}\left(\left\{u, \frac{5}{4}\left(v - \frac{3}{5}u\right), \frac{5}{3}\left(w - \frac{4}{5}u\right)\right\}\right)$

2] $M = \begin{bmatrix} a & 0 \\ b & c \end{bmatrix}$

a) For which values of (a, b, c) is this matrix diagonalizable.

Not the same } M is diagonalizable iff all eigenvalues (eigenvectors) are distinct (linearly independent).

$$\det(M - \lambda I) = \begin{vmatrix} a - \lambda & 0 \\ b & c - \lambda \end{vmatrix} = (a - \lambda)(c - \lambda)$$

$(a - \lambda)(c - \lambda) = 0$ als $\lambda_1 = a$ en $\lambda_2 = c$
 ~~M~~ M is diagonalizable if $\lambda_1 \neq \lambda_2$ and...
 So for every $a \neq c \in \mathbb{R}$ and for every $b \in \mathbb{R}$
 M is diagonalizable. ✓

b) Diagonalizable by a unitary matrix iff the matrix is normal.
 So $M^*M = MM^*$

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$$\begin{bmatrix} \bar{a} & \bar{b} \\ 0 & \bar{c} \end{bmatrix} \begin{bmatrix} a & 0 \\ b & c \end{bmatrix} = \begin{bmatrix} a & 0 \\ b & c \end{bmatrix} \begin{bmatrix} \bar{a} & \bar{b} \\ 0 & \bar{c} \end{bmatrix}$$

$$\begin{bmatrix} \bar{a}a + \bar{b}b & \bar{b}c \\ \bar{b}c & \bar{c}c \end{bmatrix} = \begin{bmatrix} a\bar{a} & a\bar{b} \\ \bar{a}b & b\bar{b} + c\bar{c} \end{bmatrix}$$

So $\bar{a}a + \bar{b}b = a\bar{a}$, $bc = ab$, $\bar{b}c = \bar{a}b$
 and $\bar{c}c = b\bar{b} + c\bar{c}$

$\bar{b}b = 0$

$c = a$ since $b = 0$ $\bar{c} = \bar{a}$

if $b = x + iy$ then $\bar{b}b = (x + iy)(x - iy) = x^2 + y^2 = 0$
 with $x, y \in \mathbb{R}$ $x^2 + y^2 = 0$ for $x, y \in \mathbb{R}$ iff $x = y = 0$ so $b = 0$

Further on now: $A^2 = U D D^H U$. Because D has all eigenvalues of A on the diagonal (which are positive or negative) ~~now~~ multiplying with D^H gives only λ^2 on diagonal.
 Now A becomes $A = (U D D^H U)^{1/2} = U^{1/2} D^{1/2} (D^H)^{1/2} U^{1/2}$

~~Best rank k approximation of A~~

Since $D^{1/2} (D^H)^{1/2}$ has got $|\lambda|^2$'s on diagonal this becomes our Σ . Further on $U^{1/2}$ is our orthogonal diagonalizer because $(U^{1/2})(U^{1/2})^H = (U U^H)^{1/2} = I$

In the above answer all H 's have to be changed by T signs so: $U^H = U^T$.

Now our SVD becomes: $A = U^{1/2} \Sigma U^{1/2}$

e)² Instead of Σ with n eigenvalues singular values on the diagonal, you have to leave k singular values on Σ for $k' > k$ all diagonal elements are 0 so

$$A = U^{1/2} \Sigma U^{1/2}$$

$$A_{(k)} = U^{1/2} \begin{pmatrix} \Sigma_k & 0 \\ 0 & 0 \end{pmatrix} U^{1/2}$$

k^{th} approximation

$$= U_k^{1/2} \Sigma_k U_k^{1/2}$$

$$4] a) f(x,y) = \sin(x) + y^3 + 3xy + 2x - 3y$$

i) $(0,-1)$ stationary point?

$$f_x = \cos x + 3y + 2$$

$$f_y = 3y^2 + 3x - 3$$

$$f_x(0,-1) = 1 - 3 + 2 = 0$$

$$f_y(0,-1) = 3 + 0 - 3 = 0$$

so $f_x = f_y = 0$
So indeed stationary point.

(ii) Hessian matrix:
$$\begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix} \Big|_{(0,-1)}$$

$$\begin{matrix} f_{xx} = -\sin x \\ f_{yy} = 6y \\ f_{xy} = 3 \\ f_{yx} = 3 \end{matrix} \Bigg\} H = \begin{bmatrix} -\sin x & 3 \\ 3 & 6y \end{bmatrix} \Big|_{(0,-1)}$$

$$= \begin{bmatrix} 0 & 3 \\ 3 & -6 \end{bmatrix}$$

Calculating eigenvalues:

$$\begin{vmatrix} -\lambda & 3 \\ 3 & -6-\lambda \end{vmatrix} = \lambda(6+\lambda) - 9 = 0$$

$$\lambda^2 + 6\lambda - 9 = 0$$

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{-6 \pm \sqrt{36 + 36}}{2} = \frac{-6 \pm \sqrt{72}}{2}$$

$$= \frac{-6 \pm 3\sqrt{8}}{2}$$

indefinite $\left\{ \begin{matrix} \lambda_1 = \frac{-6 - 3\sqrt{8}}{2} < 0 \\ \lambda_2 = \frac{-6 + 3\sqrt{8}}{2} > 0 \end{matrix} \right\}$ So because signs are not equal $(0,-1)$ is a saddle point (indefinite)

4b) ⁶ ~~7~~ A is symmetric matrix so $A^T = A$

$$\text{Since } e^A = I + A + \frac{A^2}{2!} + \frac{A^3}{3!} + \dots$$

$$\begin{aligned} (e^A)^T &= \left(I + A + \frac{A^2}{2!} + \frac{A^3}{3!} + \dots \right)^T \\ A = A^T &\longrightarrow = \left(I^T + A^T + \frac{(A^2)^T}{2!} + \frac{(A^3)^T}{3!} + \dots \right) \\ &= \left(I + A + \frac{(A^T)^2}{2!} + \frac{(A^T)^3}{3!} + \dots \right) \\ &= I + A + \frac{A^2}{2!} + \frac{A^3}{3!} + \dots \end{aligned}$$

So $e^A = (e^A)^T$ so e^A is symmetric

Assuming you mean a symmetric real matrix we have $A^H = A^T = A$. So A can be diagonalized with a unitary matrix.

$$\begin{aligned} A &= U D U^H \\ e^A &= e^{U D U^H} = I + U D U^H + \frac{(U D U^H)^2}{2!} + \dots \\ &= U \left(I + D + \frac{D^2}{2!} + \dots \right) U^H \end{aligned}$$

$$\begin{aligned} &= U e^D U^H \\ \text{Since} &= U \begin{pmatrix} e^{\lambda_1} & & \\ & e^{\lambda_2} & \\ & & \dots & \\ & & & e^{\lambda_n} \end{pmatrix} U^H \end{aligned}$$

~~Since e^{λ} is always greater than zero and e^{λ} are all on the diagonal~~

4b continued
 we have that $(e^{\lambda_i})^n$ are the eigenvalues of the matrix e^{nA} . Since e^{λ_i} is always greater than zero we have that all eigenvalues are greater than zero. So e^{nA} is positive definite.

5] $A \in \mathbb{R}^{2 \times 2}$ $p_A(\lambda) = \lambda^2 - \lambda - 1$

and $\alpha_{k+2} = \alpha_{k+1} + \alpha_k$ for $k \geq 0$

Show that $A^{n+2} = \alpha_{n+1}A + \alpha_n I$

for $n \geq 0$.

First prove for $n=0$

then $A^2 = \alpha_1 A + \alpha_0 I = A + I =$
 Because $p(\lambda) = \lambda^2 - \lambda - 1$ so $p(A) = A^2 - A - I = 0$
 So $A^2 = A + I$. So for $n=0$ the hypothesis holds.

Now assume it holds for all k . Then to prove the hypothesis we have to prove that it also holds for $k+1$.

For k
 This holds: $A^{(k+1)+2} = \alpha_{(k+1)} A + \alpha_k I$

Multiplying both sides with A gives us.

$$A^{(k+1)+2} = \alpha_{k+1} A^2 + \alpha_k A \quad \boxed{A^2 = A + I}$$

$$= \alpha_{k+1}(A + I) + \alpha_k A$$

$$= (\alpha_{k+1} + \alpha_k) A + \alpha_{k+1} I$$

Since $\alpha_{k+1} + \alpha_k = \alpha_{k+2}$ we get

$$15 \quad A^{(k+1)+2} = \alpha_{k+2} A + \alpha_{k+1} I$$

So the statement holds also for $k+1$ and thus

$$\underline{A^{n+2} = \alpha_{n+1} A + \alpha_n I \text{ holds for all } n \geq 0}$$

$$6 \quad A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$13 \quad \text{Eigenvalues} \Rightarrow \det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 2 & 3 \\ 0 & 1-\lambda & 2 \\ 0 & 0 & 1-\lambda \end{vmatrix}$$

$$= (1-\lambda)^3 = 0$$

$\lambda = 1$ with multiplicity 3

Eigenvectors: $N(A - \lambda I)$

$$\begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$0x_1 + 2x_2 + 3x_3 = 0 \Rightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$2x_3 = 0 \Rightarrow x_3 = 0$$

$$2x_2 + 3x_3 = 0$$

$$x_2 = -\frac{3}{2}x_3 \quad \text{so } x_2 = 0$$

So $x = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is only eigenvector.

Because the number of ^{Jordan} blocks is determined by the number of eigenvectors, we have that J has 1 block

So $J = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

Now the highest number k such that it is sr. ll consistent:

$$(A - I)^k s = x$$

$$(A - I)^2 = \begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 12 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{is consistent}$$

$$(A - I)^3 = \begin{bmatrix} 0 & 0 & 12 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 24 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$(A - I)^3$ and $(A - I)^2$ are equal up to a constant.

Now we can use $(A - I)^2$:

$$(A - I)^2 s = x$$

$$\begin{bmatrix} 0 & 0 & 12 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

~~Handwritten scribbles and crossed-out work, including matrix equations and vector definitions.~~

$$\begin{bmatrix} 0 & 0 & 12 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\left. \begin{array}{l} 12x_3 = 1 \\ x_3 = \frac{1}{12} \end{array} \right\} x_2 = \begin{bmatrix} 0 \\ 0 \\ \frac{1}{12} \end{bmatrix}$$

~~$$\begin{bmatrix} 0 & 0 & 12 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$~~

~~$$x_2 = \begin{bmatrix} 0 \\ 0 \\ \frac{1}{12} \end{bmatrix}$$~~

$$(A-I)x_2 = \begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \frac{1}{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{6} \\ \frac{1}{6} \\ 0 \end{bmatrix} = x_3$$

$$\text{Dus } X = [x \quad x_3 \quad x_2] = \begin{bmatrix} 1 & \frac{1}{6} & 0 \\ 0 & \frac{1}{6} & 0 \\ 0 & 0 & \frac{1}{12} \end{bmatrix}$$